Image Reconstruction in Low-Field MRI A Super-Resolution Approach **Delft University of Technology**

Merel de Leeuw den Bouter June 14, 2017

MRI scanners

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MRI scanners

- Big
- Very expensive
- Problematic in developing countries





Hydrocephalus in the developing world

Hydrocephalus

- 400.000 newborns per year
- 79% in developing countries
- Limited or no access to required healthcare



Hydrocephalus in the developing world

Hydrocephalus

- 400.000 newborns per year
- 79% in developing countries
- Limited or no access to required healthcare
- Goal: develop low-cost, portable MRI scanner



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Partners

- LUMC
- Pennsylvania State University
- Mbarara University of Science and Technology
- CURE Children's Hospital of Uganda





Outline

1 MRI

- 2 Prototypes
- 3 Super-resolution
- **4** Minimization problem
- **5** Conjugate gradient method
- 6 Simulations

7 Dataset



How does MRI work?

- Human body: $\sim 62\%$ hydrogen atoms
- H-density \Rightarrow intensity



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Image Reconstruction in Low-Field MRI

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How does MRI work?

- Spin
- Random directions
- $B_0 \Rightarrow$ net magnetic moment
- Radiofrequency pulse
- Induces signal







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Conventional vs low-field MRI

Conventional MRI

- Superconducting magnets
- Strong, homogeneous magnetic field
- High signal-to-noise ratio
- Fourier Transform

$$S(t) = \iint_{\text{object}} I(x, y) e^{-i(\gamma G_x t x + \gamma G_y T_{pe} y)} dx dy$$



Conventional vs low-field MRI

Conventional MRI

- Superconducting magnets
- Strong, homogeneous magnetic field
- High signal-to-noise ratio
- Fourier Transform

Low-field MRI

- Permanent magnets
- Weaker magnetic field with inhomogeneities
- Low signal-to-noise ratio

$$S(t) = \iint_{\text{object}} I(x, y) \omega(x, y) e^{-t/T_2^*(x, y)} e^{-i\gamma \Delta B(x, y)} dx dy$$

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$$S(t) = \iint_{\text{object}} I(x, y) \omega(x, y) e^{-t/T_2^*(x, y)} e^{-i\gamma \Delta B(x, y)} dx dy$$



$$S(t) = \iint_{\text{object}} I(x, y) \omega(x, y) e^{-t/T_2^*(x, y)} e^{-i\gamma \Delta B(x, y)} dx dy$$

discretize	
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$$S(t) = \iint_{\text{object}} I(x, y) \omega(x, y) e^{-t/T_2^*(x, y)} e^{-i\gamma \Delta B(x, y)} dx dy$$

$$s = W x$$



$$S(t) = \iint_{\text{object}} I(x, y) \omega(x, y) e^{-t/T_2^*(x, y)} e^{-i\gamma \Delta B(x, y)} dx dy$$

$$\xrightarrow{\text{discretize}} \mathbf{s} = W\mathbf{x} + \mathbf{e}$$



Prototype

LUMC

- Configuration of permanent magnets
- Inhomogeneities \Rightarrow spatial encoding

PSU

- Same components
- Inverse Fourier Transform





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PSU prototype





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Image Reconstruction in Low-Field MR

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Super-resolution

- Several low-resolution images
 - Shifted
 - Rotated
- ⇒ Obtain high-resolution image



Figure: Using LR images to obtain an HR image. Source: Van Reeth et al. (2012).

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- x: HR image
- $\{\mathbf{y}_k\}_{k=1}^N$: set of LR image observations



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- x: HR image
- $\{\mathbf{y}_k\}_{k=1}^N$: set of LR image observations



Figure: The general acquisition model. Source: Van Reeth et al. (2012).

• \Rightarrow

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- x: HR image
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Figure: The general acquisition model. Source: Van Reeth et al. (2012).

• \Rightarrow

 $G_k \mathbf{x}$

- x: HR image
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•
$$\Rightarrow$$
 $B_k G_k \mathbf{x}$

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Figure: The general acquisition model. Source: Van Reeth et al. (2012).

•
$$\Rightarrow$$
 $D_k B_k G_k \mathbf{x}$

- x: HR image
- $\{\mathbf{y}_k\}_{k=1}^N$: set of LR image observations



Figure: The general acquisition model. Source: Van Reeth et al. (2012).

• \Rightarrow $D_k B_k G_k \mathbf{x} + \mathbf{v}_k$



- x: HR image
- $\{\mathbf{y}_k\}_{k=1}^N$: set of LR image observations



Figure: The general acquisition model. Source: Van Reeth et al. (2012).

•
$$\Rightarrow$$
 $\mathbf{y}_k = D_k B_k G_k \mathbf{x} + \mathbf{v}_k$



•
$$\mathbf{y}_k = D_k B_k G_k \mathbf{x} + \mathbf{v}_k$$



•
$$\mathbf{y}_k = D_k B_k G_k \mathbf{x} + \mathbf{v}_k$$

•
$$\mathbf{y}_k = A_k \mathbf{x} + \mathbf{v}_k$$



•
$$\mathbf{y}_{k} = D_{k}B_{k}G_{k}\mathbf{x} + \mathbf{v}_{k}$$

• $\mathbf{y}_{k} = A_{k}\mathbf{x} + \mathbf{v}_{k}$
• $\mathbf{y} = \begin{pmatrix} \mathbf{y}_{1} \\ \mathbf{y}_{2} \\ \vdots \\ \mathbf{y}_{N} \end{pmatrix}, A = \begin{pmatrix} A_{1} \\ A_{2} \\ \vdots \\ A_{N} \end{pmatrix}, \mathbf{v} = \begin{pmatrix} \mathbf{v}_{1} \\ \mathbf{v}_{2} \\ \vdots \\ \mathbf{v}_{N} \end{pmatrix}$



•
$$\mathbf{y}_{k} = D_{k}B_{k}G_{k}\mathbf{x} + \mathbf{v}_{k}$$

• $\mathbf{y}_{k} = A_{k}\mathbf{x} + \mathbf{v}_{k}$
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• $\mathbf{y} = A\mathbf{x} + \mathbf{v}$

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Research question

Can super-resolution reconstruction yield images of better quality than direct high resolution reconstruction?



• v unknown



- $\mathbf{y} = A\mathbf{x} + \mathbf{v}$
- v unknown
- Ill-posed problem



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- $\mathbf{y} = A\mathbf{x} + \mathbf{v}$
- v unknown
- Ill-posed problem
- $\min_{\mathbf{x}} ||\mathbf{y} A\mathbf{x}||^2$



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•
$$\mathbf{y} = A\mathbf{x} + \mathbf{v}$$

- v unknown
- Ill-posed problem
- min $||\mathbf{y} A\mathbf{x}||^2 + \lambda ||F\mathbf{x}||^2$



- **v** unknown
- Ill-posed problem
- $\min_{\mathbf{x}} \frac{1}{2} ||\mathbf{y} A\mathbf{x}||^2 + \frac{1}{2}\lambda ||F\mathbf{x}||^2$



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- $\mathbf{y} = A\mathbf{x} + \mathbf{v}$
- v unknown
- Ill-posed problem
- $\min_{\mathbf{x}} \frac{1}{2} ||\mathbf{y} A\mathbf{x}||^2 + \frac{1}{2}\lambda ||F\mathbf{x}||^2$
- λ : regularization parameter
- F: prior knowledge about **x**



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Different kinds of regularization

• Tikhonov:

$$\min_{x} \frac{1}{2} ||\mathbf{y} - A\mathbf{x}||_{2}^{2} + \frac{1}{2}\lambda ||F\mathbf{x}||_{2}^{2}$$

• F first-order difference matrix



Different kinds of regularization

• Tikhonov:

$$\min_{x} \frac{1}{2} ||\mathbf{y} - A\mathbf{x}||_{2}^{2} + \frac{1}{2}\lambda ||F\mathbf{x}||_{2}^{2}$$

Total variation:

$$\min_{\mathbf{x}} \frac{1}{2} ||\mathbf{y} - A\mathbf{x}||_2^2 + \frac{1}{2}\lambda ||F\mathbf{x}||_1$$



Different kinds of regularization

• Tikhonov:

$$\min_{x} \frac{1}{2} ||\mathbf{y} - A\mathbf{x}||_{2}^{2} + \frac{1}{2}\lambda ||F\mathbf{x}||_{2}^{2}$$

Total variation:

$$\min_{\mathbf{x}} \frac{1}{2} ||\mathbf{y} - A\mathbf{x}||_2^2 + \frac{1}{2}\lambda ||F\mathbf{x}||_1$$

- Edge-preserving
- F first-order difference matrix



General problem statement

• Minimization problem of the form

$$\min_{\mathbf{x}} \frac{1}{2} ||\mathbf{y} - A\mathbf{x}||^2 + \frac{1}{2}\lambda ||\mathbf{x}||_R^2$$

Convex problem



General problem statement

• Minimization problem of the form

$$\min_{\mathbf{x}} \frac{1}{2} ||\mathbf{y} - A\mathbf{x}||^2 + \frac{1}{2}\lambda ||\mathbf{x}||_R^2$$

- Convex problem
- Sufficient condition for optimality:

$$(\boldsymbol{A}^{\mathsf{T}}\boldsymbol{A} + \lambda \boldsymbol{R})\mathbf{x} = \boldsymbol{A}^{\mathsf{T}}\mathbf{y}$$



General problem statement

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$$\min_{\mathbf{x}} \frac{1}{2} ||\mathbf{y} - A\mathbf{x}||^2 + \frac{1}{2}\lambda ||\mathbf{x}||_R^2$$

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- Sufficient condition for optimality:

$$(\boldsymbol{A}^{\mathsf{T}}\boldsymbol{A} + \lambda \boldsymbol{R})\mathbf{x} = \boldsymbol{A}^{\mathsf{T}}\mathbf{y}$$

• Conjugate gradient method



Conjugate gradient method

- Iterative method
- System of equations $K\mathbf{u} = \mathbf{f}$



Conjugate gradient method

- Iterative method
- System of equations $K\mathbf{u} = \mathbf{f}$
- Search directions \mathbf{p}_k conjugate wrt K ($\mathbf{p}_k K \mathbf{p}_l = 0, k \neq l$)

•
$$\mathbf{u}_{k+1} = \mathbf{u}_k + \alpha_k \mathbf{p}_k$$

•
$$||\mathbf{u} - \mathbf{u}_k||_{\mathcal{K}} = \min_{\substack{\mathbf{v} \in \mathbf{u}_0 + \\ \operatorname{span}\{\mathbf{p}_0, \dots, \mathbf{p}_{k-1}\}}} ||\mathbf{u} - \mathbf{v}||_{\mathcal{K}}$$



Phantom (128 x 128 pixels)



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Image Reconstruction in Low-Field MRI

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Shifted



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Merel de Leeuw den Bouter (TU Delft)

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Blurred



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Down-sampled





Noise added



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4 low resolution images $(32 \times 32 \text{ pixels})$



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- $\mathbf{s} = W\mathbf{x} + \mathbf{e}$
- Angles $0^\circ, 10^\circ, ..., 350^\circ$
- Signal-to-noise ratios starting from 0.5







Model solution



Direct HR solution (SNR = 10)



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Model solution



Direct HR solution (SNR = 0.5)



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LR images (8 \times 8 pixels)



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Image Reconstruction in Low-Field MRI

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HR solution



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SR solution



HR solution



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- Goal
 - Application to real data
 - Validation of the model
- 7 T MRI scanner
- Gradient in one direction
- 16 angles



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Model solution



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Model solution

First 1D projection



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16 1D projections



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Model solution



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Model solution



Result

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Model solution





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× 10⁻¹⁴ 2.5 ×10⁶ 1.5 0.5

Model solution

Result

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Conclusions and further research

Conclusions

- Super-resolution can yield better results
- Total variation regularization
- Validation of the measurement model



Conclusions and further research

Conclusions

- Super-resolution can yield better results
- Total variation regularization
- Validation of the measurement model
- Further research
 - Apply super-resolution to PSU data
 - New LUMC prototype
 - Measurements at LUMC with more complicated field
 - Dictionary learning



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LUMC dataset: super-resolution



Merel de Leeuw den Bouter (TU Delft)

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