

Development of the Helmholtz Solver based on Schwarz Domain Decomposition Preconditioning

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Introduction

The inhomogeneous wave equation is

$$\left(\frac{\partial^2}{\partial t^2} - c^2 \nabla^2 \right) u(\mathbf{x}, t) = f(\mathbf{x}), \mathbf{x} \in \mathbb{R}^d \quad (1)$$

Separation of variables leads to

$$\begin{aligned} (-\nabla^2 - k^2) \phi(\mathbf{x}) &= f(\mathbf{x}), \\ k &= \frac{2\pi}{\lambda}. \end{aligned} \quad (2)$$

$$f(\mathbf{x}) = \delta(\mathbf{x} - \mathbf{x}_0).$$

Helmholtz Boundary Value Problems

(BVP-1):

$$\begin{cases} (-\nabla^2 - k^2) u(\mathbf{x}) = \delta(\mathbf{x} - \mathbf{x}_0), & \text{in } \Omega \in \mathbb{R}^d. \\ u(\mathbf{x}) = 0 & \text{for } \mathbf{x} \in \partial\Omega, \\ k \in \mathbb{N} \setminus \{0\} \text{ and } d \in \{1, 2, 3\}. \end{cases} \quad (3)$$

(BVP-2):

$$\begin{cases} (-\nabla^2 - k^2) u(\mathbf{x}) = \delta(\mathbf{x} - \mathbf{x}_0), & \text{in } \Omega \in \mathbb{R}^d. \\ \left(\frac{\partial u(\mathbf{x})}{\partial \mathbf{n}} - iku(\mathbf{x}) \right) = 0, & \text{for } \mathbf{x} \in \partial\Omega, \\ k \in \mathbb{N} \setminus \{0\} \text{ and } d \in \{1, 2, 3\}. \end{cases} \quad (4)$$

Finite Difference Discretization

Assume we have BVP-1 on unit domain Ω and $h = \frac{1}{n}$.

$$A\mathbf{u} = \mathbf{f}, \text{ on } \Omega. \quad (5)$$

- A becomes indefinite for large wave numbers.
- Iterative solution methods, GMRES

Numerical Solver Problems

- Pollution Error.
 - Accuracy issue of the solution.
 - Refinement requirements ¹ ².
 $kh < 1$, or even better $k^3 h^2 \leq 1$ with
- Problem size increasing with the wave number k .

¹A. Sheikh (2014). "Development Of The Helmholtz Solver Based On A Shifted Laplace Preconditioner And A Multigrid Deflation Technique". [Thesis](#)

²A. Deraemaeker, I. Babuska, and P. Bouillard (1999). "Dispersion and pollution of the FEM solution for the Helmholtz equation in one, two and three dimensions". In: *INTERNATIONAL JOURNAL FOR NUMERICAL METHODS IN ENGINEERING* 46.4, pp. 471–499

Helmholtz solvers

Attempts at wave-number-independent solvers

- Adapted preconditioned DEF Scheme (APD) (Deflation Preconditioner)³
- Two-Level Domain Decomposition Preconditioner with grid coarse space and DtN coarse space⁴

³V. Dwarka and C. Vuik (2020). “Scalable convergence using two-level deflation preconditioning for the helmholtz equation”. In: *SIAM Journal on Scientific Computing* 42.2, A901–A928. ISSN: 1064-8275

⁴M. Bonazzoli, V. Dolean, I. G. Graham, E. A. Spence, and P. H. Tournier (2018). “Two-level preconditioners for the helmholtz equation”. In: *Lecture Notes in Computational Science and Engineering*. Vol. 125. Springer Verlag, pp. 139–147. ISBN: 14397358 (ISSN), DOI: 10.1007/978-3-319-93873-8_11

One-Level Schwarz Preconditioner

2D Unit Square Domain

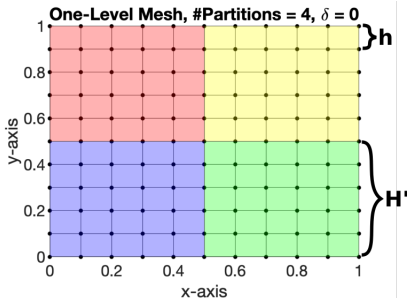


Figure: Non-overlapping subdomains

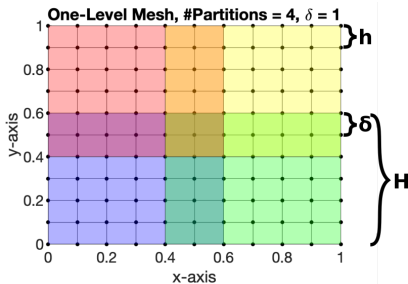


Figure: Overlapping subdomains

One-Level Schwarz Preconditioner

We introduce discrete projection-like operators as

$$P_i = R_i^T A_i^{-1} R_i, \quad \text{for } i = 1, \dots, N \quad (6)$$

Multiplicative Schwarz operator:

$$M_{\text{MS}}^{-1} = I - (I - P_N)(I - P_{N-1}) \dots (I - P_1). \quad (7)$$

Additive Schwarz operator:

$$M_{\text{AS}}^{-1} = \sum_{i=1}^N P_i = \sum_{i=1}^N R_i^T A_i^{-1} R_i. \quad (8)$$

Upper bound for condition number preconditioner system:

$$\kappa(M_{\text{AS}}^{-1}A) \leq C \left(\frac{1}{\delta^2 H^2} \right), \quad (9)$$

Two-Level Schwarz Preconditioner

Introduce a coarse space, which gives the two-level additive Schwarz operator is of the form

$$M_{AS2}^{-1} = \sum_{i=0}^N P_i = R_0^T A_0^{-1} R_0 + \sum_{i=1}^N R_i^T A_i^{-1} R_i, \quad (10)$$

Leads to new upper bound for condition number

$$\kappa(M_{AS2}^{-1}A) \leq C \left(1 + \frac{H}{\delta}\right) \quad (11)$$

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$$\kappa(M_{AS2}^{-1}A) \leq C \left(1 + \frac{H}{\delta}\right) \quad (11)$$

This upper bound for the condition number is **parallel scalable!**

GDSW Preconditioner

Advantages of using GDSW:

- More freedom in constructing the coarse grid,
- GDSW coarse spaces are flexible in adding additional coarse functions,
- The GDSW preconditioner only requires the trace of the interface.

GDSW Preconditioner

R_0 from Equation (10) is replaced by Φ giving the operator

$$M_{\text{GDSW}}^{-1} = \sum_{i=0}^N P_i = \Phi^T A_0^{-1} \Phi + \sum_{i=1}^N R_i^T A_i^{-1} R_i, \quad (12)$$

with

$$\kappa(M_{\text{GDSW}}^{-1} A) \leq C \left(1 + \frac{H}{\delta}\right) \left(1 + \log\left(\frac{H}{h}\right)\right)^2, \quad (13)$$

and for certain GDSW coarse space we even find

$$\kappa(M_{\text{GDSW}}^{-1} A) \leq C \left(1 + \frac{H}{\delta}\right). \quad (14)$$

Deflation

Higher-order coarse correction operator

Deflation:

$$P_D = I - P = I - AZ(E)^{-1}Z^T, \quad Z \in \mathbb{R}^{(n+1)^d \times r^d}. \quad (15)$$

For APD preconditioner: coarse correction operator $Z = I_{2h}^h$ with weight ε

$$I_{2h}^h [u_{2h}]_i = \begin{cases} \left(\frac{1}{8} [u_{2h}]_{(i-2)/2} + \left(\frac{3}{4} - \varepsilon\right) [u_{2h}]_{(i)/2} + \frac{1}{8} [u_{2h}]_{(i+2)/2} \right) & \text{if } i \text{ is even,} \\ \frac{1}{2} \left([u_{2h}]_{(i-1)/2} + [u_{2h}]_{(i+1)/2} \right) & \text{if } i \text{ is odd} \end{cases} \quad (16)$$

Quadratic approximation using the rational Bézier curve.

Parallel Computing

- More memory storage,
- better computational performance.

Distributed memory message-passing models using the MPI library.

Trilinos: software suite with robust, scalable, parallel solver algorithms.

FROSch: Schwarz preconditioner with GDSW-type coarse space.

Test Problem Domain Decomposition Preconditioner

One-Level Additive Schwarz Preconditioner

Note: 2D Poisson problem unit square domain.

$H' (\delta = 1)$	$n^2 = 6400$	$n^2 = 25600$
0.5	17	22
0.25	24	33
0.125	30	43
0.0625	45	50+

Table: Number of GMRES iterations for the test problem using a one-level AS preconditioner.

Research Questions 1

Does a Helmholtz solver that uses a two-level additive Schwarz preconditioner combined with **first-order** grid coarse space show **numerical scalability** and **efficiency**?

- What causes the solver to be inscalable?

Research Questions 2

Does a Helmholtz solver that uses a two-level additive Schwarz preconditioner and a **higher-order** coarse space from the **deflation setting** show **numerical scalability** and **efficiency**?

- What causes the solver to be inscalable if this is the case?
- How much better does the Helmholtz solver perform when the **higher-order coarse space from the deflation setting** is used as the **multiplicative** coupling of the coarse level?

Research Questions 3

When using higher-order coarse spaces shows promising performance, does using a **GDSW-type coarse space**, improve the Helmholtz solver further?

- Can higher-order coarse spaces be used in GDSW-type coarse spaces?
- Does this solver show improved performance?

Research Questions 4

If time permits, does the numerically scalable and efficient Helmholtz solver show **parallel scalability** when it is transformed into a **parallel algorithm**? To do this we could use **FROSch** of **Trilinos**.

- Do memory or communication problems arise?
- How much does a restricted additive Schwarz preconditioner improve the parallel algorithm further?