

**ANSWERS OF THE TEST NUMERICAL METHODS FOR  
DIFFERENTIAL EQUATIONS (WI3097 TU)  
Thursday August 15, 2013, 18:30-21:30**

1.

a The local truncation error is defined as

$$\tau_{n+1}(h) = \frac{y_{n+1} - z_{n+1}}{h}, \quad (1)$$

where  $z_{n+1}$  is given by

$$z_{n+1} = y_n + h(a_1 f(t_n, y_n) + a_2 f(t_n + h, y_n + h f(t_n, y_n))). \quad (2)$$

A Taylor expansion of  $f$  around  $(t_n, y_n)$  yields

$$f(t_n + h, y_n + h f(t_n, y_n)) = f(t_n, y_n) + h \frac{\partial f}{\partial t}(t_n, y_n) + h f(t_n, y_n) \frac{\partial f}{\partial y}(t_n, y_n) + O(h^2). \quad (3)$$

This is substituted into equation (2) to obtain

$$z_{n+1} = y_n + h \left( a_1 f(t_n, y_n) + a_2 \left[ f(t_n, y_n) + h \frac{\partial f}{\partial t}(t_n, y_n) + h f(t_n, y_n) \frac{\partial f}{\partial y}(t_n, y_n) \right] \right) + O(h^3). \quad (4)$$

A Taylor series for  $y(x)$  around  $t_n$  gives for  $y_{n+1}$

$$y_{n+1} = y(t_n + h) = y_n + h y'(t_n) + \frac{h^2}{2} y''(t_n) + O(h^3). \quad (5)$$

From the differential equation we know that:

$$y'(t_n) = f(t_n, y_n) \quad (6)$$

From the Chain Rule of Differentiation, we derive

$$y''(t_n) = \frac{df(t_n, y_n)}{dt} = \frac{\partial f(t_n, y_n)}{\partial t} + \frac{\partial f(t_n, y_n)}{\partial y} y'(t_n) \quad (7)$$

after substitution of the differential equation one obtains:

$$y''(t_n) = \frac{\partial f(t_n, y_n)}{\partial t} + \frac{\partial f(t_n, y_n)}{\partial y} f(t_n, y_n) \quad (8)$$

Equations (5) and (4) are substituted into relation (1) to obtain

$$\tau_{n+1}(h) = f(t_n, y_n)(1 - (a_1 + a_2)) + h \left( \frac{\partial f}{\partial t} + f \frac{\partial f}{\partial y} \right) \left( \frac{1}{2} - a_2 \right) + O(h^2) \quad (9)$$

Hence

- (a)  $a_1 + a_2 = 1$  implies  $\tau_{n+1}(h) = O(h)$ ;  
 (b)  $a_1 + a_2 = 1$  and  $a_2 = 1/2$ , that is,  $a_1 = a_2 = 1/2$ , gives  $\tau_{n+1}(h) = O(h^2)$ .

b The test equation is given by

$$y' = \lambda y. \quad (10)$$

Application of the predictor step to the test equation gives

$$w_{n+1}^* = w_n + h\lambda w_n = (1 + h\lambda)w_n. \quad (11)$$

The corrector step yields

$$w_{n+1} = w_n + h(a_1\lambda w_n + a_2\lambda(1 + h\lambda)w_n) = (1 + (a_1 + a_2)h\lambda + a_2h^2\lambda^2)w_n. \quad (12)$$

Hence the amplification factor is given by

$$Q(h\lambda) = 1 + (a_1 + a_2)h\lambda + a_2h^2\lambda^2. \quad (13)$$

c Let  $\lambda < 0$  (so  $\lambda$  is real), then, for stability, the amplification factor must satisfy

$$-1 \leq Q(h\lambda) \leq 1, \quad (14)$$

from the previous assignment, we have

$$-1 \leq 1 + (a_1 + a_2)h\lambda + a_2(h\lambda)^2 \leq 1 \Leftrightarrow -2 \leq (a_1 + a_2)h\lambda + a_2(h\lambda)^2 \leq 0. \quad (15)$$

First, we consider the left inequality:

$$a_2(h\lambda)^2 + (a_1 + a_2)h\lambda + 2 \geq 0 \quad (16)$$

For  $h\lambda = 0$ , the above inequality is satisfied, further the discriminant is given by  $(a_1 + a_2)^2 - 8a_2 < 0$ . Here the last inequality follows from the given hypothesis. Hence the left inequality in relation (15) is always satisfied. Next we consider the right hand inequality of relation (15)

$$a_2(h\lambda)^2 + (a_1 + a_2)h\lambda \leq 0. \quad (17)$$

This relation is rearranged into

$$a_2(h\lambda)^2 \leq -(a_1 + a_2)h\lambda, \quad (18)$$

hence

$$a_2|h\lambda|^2 \leq (a_1 + a_2)|h\lambda| \Leftrightarrow |h\lambda| \leq \frac{a_1 + a_2}{a_2}, \quad a_2 \neq 0. \quad (19)$$

This results into the following condition for stability

$$h \leq \frac{a_1 + a_2}{a_2|\lambda|}, \quad a_2 \neq 0. \quad (20)$$

d The Jacobian,  $J$ , is given by

$$J = \begin{pmatrix} \frac{\partial f_1}{\partial y_1} & \frac{\partial f_1}{\partial y_2} \\ \frac{\partial f_2}{\partial y_1} & \frac{\partial f_2}{\partial y_2} \end{pmatrix}. \quad (21)$$

Since  $f_1(y_1, y_2) = -y_1y_2$  and  $f_2(y_1, y_2) = y_1y_2 - y_2$ , we obtain

$$J = \begin{pmatrix} -y_2 & -y_1 \\ y_2 & y_1 - 1 \end{pmatrix}. \quad (22)$$

Substitution of the initial values  $y_1(0) = 1$  and  $y_2(0) = 2$ , gives

$$J = \begin{pmatrix} -2 & -1 \\ 2 & 0 \end{pmatrix}. \quad (23)$$

e The eigenvalues of the Jacobian at  $y_1(0) = y_2(0) = 1$  are given by  $\lambda_{1,2} = -1 \pm i$ . For our case, we have

$$Q(h\lambda) = 1 + h\lambda + 1/2(h\lambda)^2. \quad (24)$$

Since our eigenvalues are not real valued, it is required for stability that

$$|Q(h\lambda)| \leq 1. \quad (25)$$

Since the eigenvalues are complex conjugates, we can proceed with one of the eigenvalues, say  $\lambda = -1 + i$  with  $\lambda^2 = -2i$  to obtain

$$Q(h\lambda) = 1 + h(-1 + i) + 1/2h^2(-2i) \quad (26)$$

Substitution of  $h = 1$  shows that  $Q(h\lambda) = 0$ . This implies that  $|Q(h\lambda)| = 0 \leq 1$  so the method is stable.

2. a First, we check the boundary conditions:

$$u(0) = \frac{e^0 - 1}{e - 1} = \frac{1 - 1}{e - 1} = 0, \quad u(1) = \frac{e^1 - 1}{e - 1} = 1. \quad (27)$$

Further, we have

$$u'(x) = \frac{e^x}{e - 1} = u''(x). \quad (28)$$

Hence, we immediately see

$$-u''(x) + u'(x) = -\frac{e^x}{e - 1} + \frac{e^x}{e - 1} = 0. \quad (29)$$

Hence, the solution  $u(x) = \frac{e^x - 1}{e - 1}$  satisfies the differential and the boundary conditions, and therewith  $u(x)$  is the solution to the boundary value problem (uniqueness can be demonstrated in a straightforward way, but this was not asked for).

b) The domain of computation, being  $(0, 1)$ , is divided into subintervals with mesh-points, we set  $x_j = jh$ , where we use  $n$  unknowns, such that  $x_{n+1} = (n+1)h = 1$ . We are looking for a discretization with an error of second order,  $O(h^2)$ . To this extent, we use the following central differences approximation at  $x_j$ :

$$u'(x_j) \approx \frac{u(x_{j+1}) - u(x_{j-1}))}{2h}, \text{ for } j \in \{1, \dots, n\}. \quad (30)$$

We note that the above formula can be derived formally by writing the derivative as

$$u'(x_j) = \frac{\alpha_0 u(x_{j-1}) + \alpha_1 u(x_j) + \alpha_2 u(x_{j+1}))}{h}, \quad (31)$$

and solve  $\alpha_0$ ,  $\alpha_1$  and  $\alpha_2$  from checking the zeroth, first and second order derivatives of  $u(x)$ . Further, the second order derivative is approximated by

$$u''(x_j) \approx \frac{u(x_{j+1}) - 2u(x_j) + u(x_{j-1}))}{h^2}. \quad (32)$$

Since we approximate the derivatives at the point  $x_j$ , we use Taylor Series around  $x_j$ , to obtain:

$$\begin{aligned} u(x_{j+1}) &= u(x_j + h) = u(x_j) + hu'(x_j) + \frac{h^2}{2}u''(x_j) + \frac{h^3}{6}u'''(x_j) + \frac{h^4}{24}u''''(x_j) + O(h^5), \\ u(x_{j-1}) &= u(x_j - h) = u(x_j) - hu'(x_j) + \frac{h^2}{2}u''(x_j) - \frac{h^3}{6}u'''(x_j) + \frac{h^4}{24}u''''(x_j) + O(h^5), \end{aligned} \quad (33)$$

This gives

$$\begin{aligned} -\frac{u(x_{j+1}) - 2u(x_j) + u(x_{j-1}))}{h^2} + \frac{u(x_{j+1}) - u(x_{j-1}))}{2h} &= -u''(x_j) + u'(x_j) \\ + \frac{\frac{h^3}{3}u'''(x_j) + O(h^4)}{2h} + \frac{\frac{h^4 u''''(x_j)}{12} + O(h^5)}{h^2} &= -u''(x_j) + u'(x_j) + O(h^2). \end{aligned} \quad (34)$$

Hence the error is second order, that is  $O(h^2)$ . Next, we neglect the truncation error, and set  $v_j := u(x_j)$  to get

$$-\frac{v_{j+1} - 2v_j + v_{j-1}}{h^2} + \frac{v_{j+1} - v_{j-1}}{2h} = 0, \text{ for } j \in \{1, \dots, n\}. \quad (35)$$

At the boundaries, we see for  $j = 1$  and  $j = n$ , upon substituting  $v_0 = 0$  and  $v_{n+1} = 1$ :

$$\begin{aligned} -\frac{v_2 - 2v_1 + 0}{h^2} + \frac{v_2 - 0}{2h} &= 0, \\ -\frac{1 - 2v_n + v_{n-1}}{h^2} + \frac{1 - v_{n-1}}{2h} &= 0. \end{aligned} \quad (36)$$

This is rewritten more neatly by

$$\begin{aligned} \frac{-v_2 + 2v_1}{h^2} + \frac{v_2}{2h} &= 0, \\ \frac{2v_n - v_{n-1}}{h^2} - \frac{v_{n-1}}{2h} &= \frac{1}{h^2} - \frac{1}{2h}. \end{aligned} \tag{37}$$

c Since the exact solution is given by

$$u(x) = \frac{e^x - 1}{e - 1}, \tag{38}$$

we immediately see that the exact solution is a real-valued exponential, which is monotonic by its nature. Since the numerical solution should have the same characteristics as the exact solution, non-monotonic (and hence oscillatory) solutions should be considered as not reflecting the analytic solution.

d i The magnitude of the local truncation error is given by

$$|\varepsilon| = \left| \int_a^b f(x)dx - \frac{b-a}{2} (f(a) + f(b)) \right|. \tag{39}$$

We use linear interpolation over the interval  $(a, b)$ , which gives

$$f(x) - \left( f(a) \frac{x-b}{a-b} + f(b) \frac{x-a}{b-a} \right) = \frac{1}{2} (x-a)(x-b) f''(\xi), \text{ for a } \xi \in (a, b) \setminus \{x\}. \tag{40}$$

Since

$$\int_a^b \left( f(a) \frac{x-b}{a-b} + f(b) \frac{x-a}{b-a} \right) dx = \frac{b-a}{2} (f(a) + f(b)), \tag{41}$$

this implies that

$$\begin{aligned} \left| \int_a^b f(x)dx - \frac{b-a}{2} (f(a) + f(b)) \right| &= \left| \int_a^b \frac{1}{2} (x-a)(x-b) f''(\xi(x)) dx \right| \\ &\leq \frac{1}{2} \int_a^b (x-a)(b-x) |f''(\xi(x))| dx \leq \frac{M}{2} \int_a^b (x-a)(b-x) dx. \end{aligned} \tag{42}$$

Continuity, and hence boundedness, of the second-order derivatives on the interval  $(0, 1)$  implies the existence of an  $M > 0$  such that  $|f''(x)| \leq M$  on the interval  $(a, b)$ , since the derivatives of  $f$  up to second order are bounded. Furthermore, we have

$$\int_a^b (x-a)(x-b) dx = \frac{(b-a)^3}{6}, \tag{43}$$

by which we finally conclude

$$\left| \int_a^b f(x)dx - \frac{b-a}{2} (f(a) + f(b)) \right| \leq \frac{M}{12} (b-a)^3, \quad (44)$$

where, as we saw earlier,  $M$  is an upper bound for the second order derivative on the interval  $(a, b)$ .

ii Application over the gridnodes  $\{x_j\}$ , with gridspacing  $h$ , gives

$$\begin{aligned} \int_0^{0.3} f(x)dx &\approx \sum_{j=1}^n \int_{x_{j-1}}^{x_j} f(x)dx = \sum_{j=1}^n \frac{h}{2} (f(x_{j-1}) + f(x_j)) \\ &= h \left( \frac{f(x_0)}{2} + f(x_1) + \dots + f(x_{n-1}) + \frac{f(x_n)}{2} \right). \end{aligned} \quad (45)$$

Application to the current situation, with  $h = 0.1$ ,  $n = 3$ , and the tabular values, gives

$$\int_0^{0.3} f(x)dx \approx 0.1 \left( \frac{0}{2} + 0.01 + 0.04 + \frac{0.09}{2} \right) = 0.0095. \quad (46)$$